

Speedpilet.

Fitting instructions

Halda Speed Pilot can be fitted to all existing makes of cars, commercial vehicles and buses. The fitting frame supplied makes the installation a simple job — this frame is usually screwed to the underside of the dashboard in a position where the Speed Pilot can be seen by the driver at a glance.

The most suitable position will naturally vary with different cars — it can be on one side or other of the steering column but if it can be placed between the driver and the front passenger, this will enable the latter to se the Pilot also.

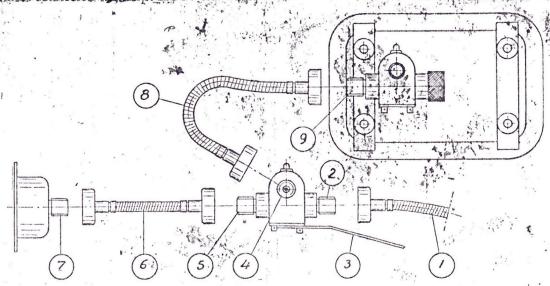
The Pilot is fastened into the fitting frame by means of the metal straps and the frame can be bent to a certain extent to give the Pilot the most suitable angle when fitted.

Some car owners may prefer to fit the Pilot into the dashboard panel. In this case an aperture $3'' \times 5''$ (75 mm × 125 mm) must be made — the Pilot is fitted into this and fastened by means of the metal straps.

On some cars fitted with floor type gear levers and with little leg room — lack of space may not allow of fitting between driver and passenger and so dashboard fitting may sometimes be essential.

Attachment of Speed Pilot

The Pilotis connected to the speed ometer of the ca



- 1. Speedometer cable (1) is detached from speedometer head (7) and is attached instead to the T-gear box (2) supplied.
- 2. The cable (6) from the T-gear box (5) is connected in turn to the speedometer (7). Make sure in both cases that there is not too much tension. The cable should be able to rotate easily.
- 3. T-gearbox is now fixed in suitable place. See when this is done that the transmission lies in as straight a line as possible.
- 4. Separate cable (8) which is supplied is for connecting between T-gearbox (4) and the gear box (9) on the back of the Speed Pilot.

Note This gearbox can be rotated—it should be locked by tightening the nut between the speed pilot and the gearbox keeping the transmission in as straight a line as possible.

Electric connection

Since some cars have 6 and others 12 volt system, lamps are not supplied with Speed Pilot. The correct lamp should be fitted and the lamp contact connected to the switch controlling the Dashboard light.

Adjustment

The Speed Pilot is driven from the speedometer drive. The number of revolutions of the speedometer drive to the mile or kilometer varies with different makes of car.

The gearing of the Speed Pilot must be adjusted therefore in accordance with the speedometer revs in each case.

The required adjustment can be carried out very quickly by means of the adjustment screw fitted on the underside of the Speed Pilot.

Each Pilot is adjusted on delivery to the equivalent of 900 revs of the speedometer to one mile or 576 revs per kilometer.

Do not disturb the adjustment screw before you have ascertained the speedometer revs of the car to which it will be fitted. This information is usually given on the face of the speedometer.

If the actual speedo revs of the car are 576 per km or 900 per mile, then the Speed Pilot is correctly adjusted, and thus it will not be necessary to touch the adjustment screw.

Should the speedo drive revs be *more* than 576 per km or 900 per mile, then the adjustment screw must be moved a certain number of turns on the adjustment scale to minus (—). If the speedometer revs should be *less*, then the adjustment screw must be moved a certain number of turns towards plus (+).

The number of turns of the adjustment screw required is given in the following table — this covers the speedo revs most commonly met with both for miles and kilometers.

'ADJUSTMENT TABLE

*	ADJUSTME		
MILES		KILOMETRES	
Speedo Revs per mile	Number of turns on adjustment screw	Speedo Revs per kilometre	Number of turns on adjustment screw
546 642 800 900 1900 1012 1040 1100 1140 1180 1300 1325 1375 1400 1425 1475 1500 1525 1550 1575 1600 1650 1675	64,8 towards + 40,2	510 550 560 565 576 585 590 595 600 601,34 605 610 615 620 625 630 632,5 633 632,5 640 645 650 655 658 720 747 795 820 840 845 870 895 900 920 940 1000 1020 1030 1040 1055 1080 1090 1240	13 towards + 4,7

After adjustment in accordance with the table, the Speed Pilot is theoretically correct. In practice however, the accuracy pend an animber of other factors also — for instance that tyre size and tyre pressures are correct, or even that the speedometer works within reasonable tolerance of the revs per mile or km indicated.

It is therefore desirable to theck that the Speed Pilotis correct in operation — it can be adjusted to 99.5 %

The best check is to test against a measured toad distance, but check can also be made against the mileage register of the speedometer.

In the latter case the degree of accuracy cannot of course be greater than that of the speedometer.

For normal purposes this is quite see that, but for competition use or any other case where extreme accuracy is required check should be made leainst a measured road diastance.

For final correction the adjustment screw is again used - procedure being as follows:

If the trip counter of the Pilot shows more than the measured road distance then the adjustment screw must be turned towards minus (-).

If the trip counter of the Pilot shows less than the measured road distance then the adjustment screw must be turned towards plus (+).

It is suggested that the customer should be shown the adjustment screw and given instructions for correcting his Speed Pilot.

Most customers are bound to appreciate knowing something about their Speed Pilot and particularly how to adjust it for the greatest possible accuracy.

Formula for Final Adjustment

To make the final adjustment after road test to bring the Speed Pilot to an accuracy of 99.5% the following simple formulas should be used. They will enable you to work out exactly how much the adjustment screw has to be turned and they are the same for both miles and kilometres.

The number of turns of the adjustment screw required we call "N". The distance shown on the Pilot tripmeter we call "I". The distance we call "D":

We give two typical cases that can occur and they are worked out as follows.

Pilot trip meter shows more than the actual distance

The screw must be turned towards minus (-)

$$N = \frac{100 \cdot (T - D)}{T}$$

Example Actual distance D=3. Trip meter shows T=3,1.

Substituting these figures in the formula gives

$$N = \frac{100 \cdot (3,1-3)}{3,1} = \frac{100 \cdot 0,1}{3,1} = \frac{10}{3,1} = 3,23$$

The screw must thus be moved 3,23 turns towards minus (—).

Pilot trip meter shows less than the actual distance

The screw must be turned towards plus (+)

$$N = \frac{100 \cdot (D - T)}{T}$$

Example Actual distance D=3. Trip meter shows T=2,9.

Substituting these figures in the formula gives

$$N = \frac{100 \cdot (3 - 2.9)}{2.9} = \frac{100 \cdot 0.1}{2.9} = \frac{10}{2.9} = 3,45$$

The screw must thus be moved 3,45 turns towards plus (+).

P. S.

Formula for Primary Adjustment

For those cases where the figure for Speedometer revs is one which does not appear in the table given above, the required number of turns of the adjustment screw can be worked out by means of the formulas given below.

If we call the number of turns required "N" and the actual speedometer revs "R" then we have the following formulas for miles and kilometres respectively.

Formula for Miles

1. R is greater than 900 revs per mile.

$$N = 100 - \frac{90.000}{R}$$

R is less than 900 revs per mile.

$$N = \frac{90.000}{R} - 100$$

Example of 1) above:

R proves to be 1.000 revs per mile.

$$N = 100 - \frac{90.000}{1.000}$$

Worked out this becomes

$$N = 100 - 90$$
; $N = 10$

The adjustment screw must thus be moved 10 turns towards minus (-).

Example of 2) above:

R proves to be 750 revs per mile

$$N = \frac{90.000}{750} - 100$$

Worked out this becomes

$$N = 120 - 100$$
; $N = 20$

 $N=120-100;\ N=20$ The adjustment set of must thus be moved 20

Formula for Kilometres

· R is greater than 576 revs per kilometre.

$$N = 100 - \frac{57.600}{R}$$

R is less than 576 revs per kilometre.

$$N = \frac{57.600}{R_0} - 100$$

Example of 1) above:

R proves to be 640 revs per kilometre

$$N = 100 - \frac{57.600}{640}$$

Worked out this becomes

$$N = 100 - 90; N = 10$$

The adjustment screw must thus be moved 10 turns towards minus (--).

Example of 2) above:

R proves to be 522 revs per Km.

$$N = \frac{57.600}{522} - 100$$

Worked out this becomes

$$N = 110,3 - 100; N = 10,3$$

The adjustment screw must thus be moved 10,3

A red label made of selfreflecting scotchlife and with the word "SPEED-PILOT" printed on it, is supplied with each instrument. Stick this label to the back of the car.



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